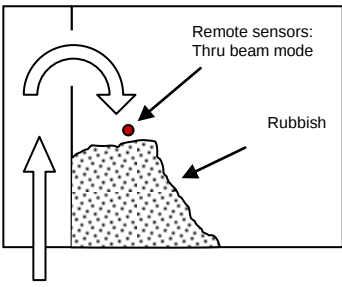
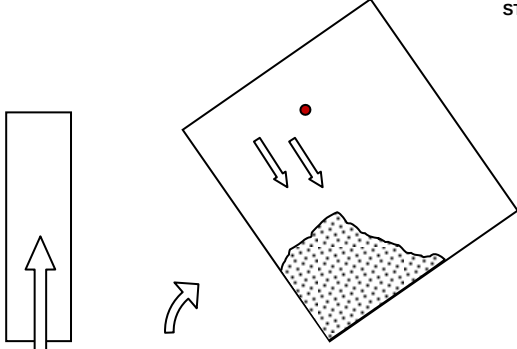
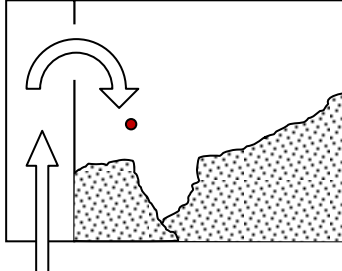


Applications

Industry / Customer Group	Miscellaneous
Application	Road sweepers – level detection
Country	Italy
Product	PA 11 – LT/LR 120
Variations	PA 15 – PAB 10
Application STEP 1  Remote sensors: Thru beam mode Rubbish Dust, dirt and rubbish suctioned up from the street. 	
STEP 2  When rubbish blocks the beam the container tilts and the rubbish falls to the back of the container. STEP 3  The container returns to its normal position and the road sweeper continues cleaning.	
Details The remote sensors are installed in thru beam mode, inside the container/deposit of the road sweeper. Step 1: The dirt, dust and rubbish are dropped at the front of the container. Step 2: When the level reaches the sensors, the operator is informed by an optical indicator on the front panel. The operator activates the mechanism to tilt the container to move the rubbish to the back. Step 3: The container returns to its normal position and the operator can continue. In this particular application the customer used the “on time delay” in the PA amplifier in order to avoid possible false outputs and to ensure that the level has been reached.	
Reference: TELCO 1201031045	

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